

Network Stochastic Programming

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The Research Project

- Motivation
- Previous Research
- Network Stochastic Programming
 - Upper Bound
 - Lower Bound



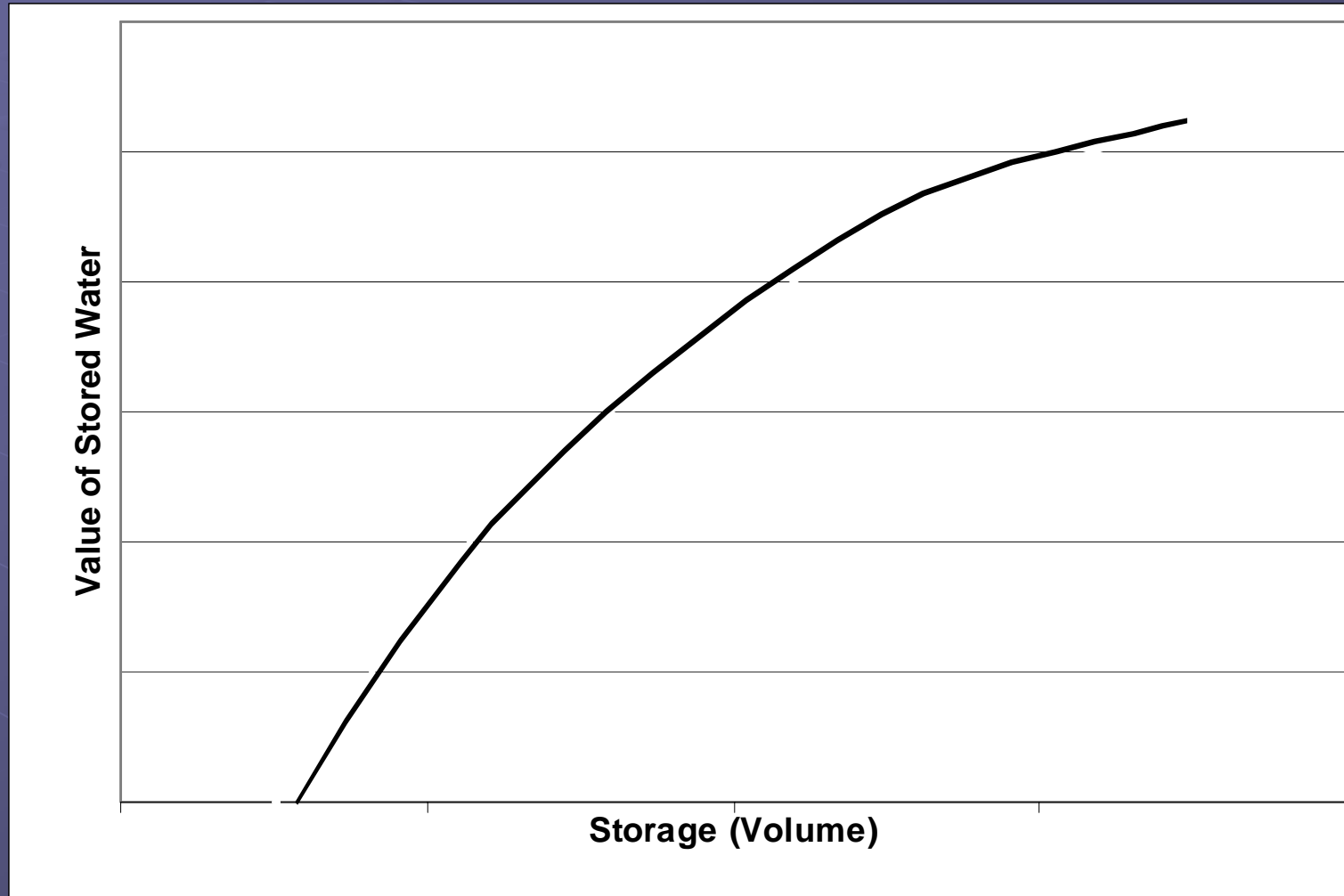
Basic Optimization Approach

- Optimization based on 1 week model: current value plus future value
- obj:
 - Max avoided cost + future value
- Existing Model: future value is input (from VPS)
- New Model: future value based on alternative hydrologic scenarios for future weeks

Value of Project Storage

- One curve produced per reservoir
- No interaction between reservoirs is considered
- System wide operation so clearly there is reservoir interaction
 - ex: One very high reservoir, rest very low
Operation decisions very different

Value of water vs. Storage (exaggerated curve, not to scale)



Stochastic Nature of Inflow

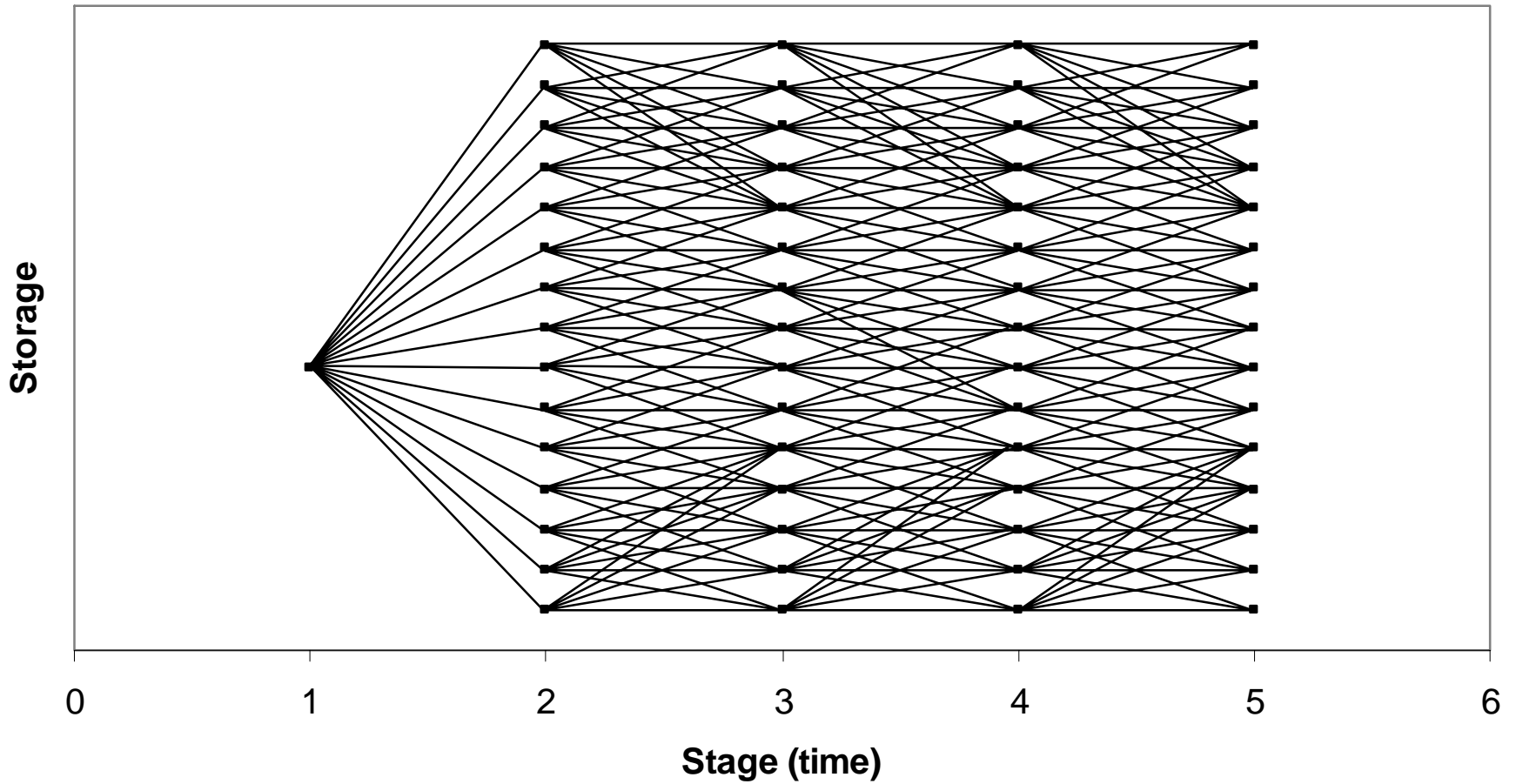
- Because the future value of water depends on uncertain future hydrologic inflow, the model is by nature stochastic
- Optimizing reservoir scheduling with regard to uncertainty in inflows is a ***Stochastic Optimization*** problem

Previous Research

- Two Approaches have historically dominated this classification:
 1. Stochastic Dynamic Programming (SDP)
 2. Stochastic Programming with Recourse (SPR)

SDP (cont.)

SDP Network



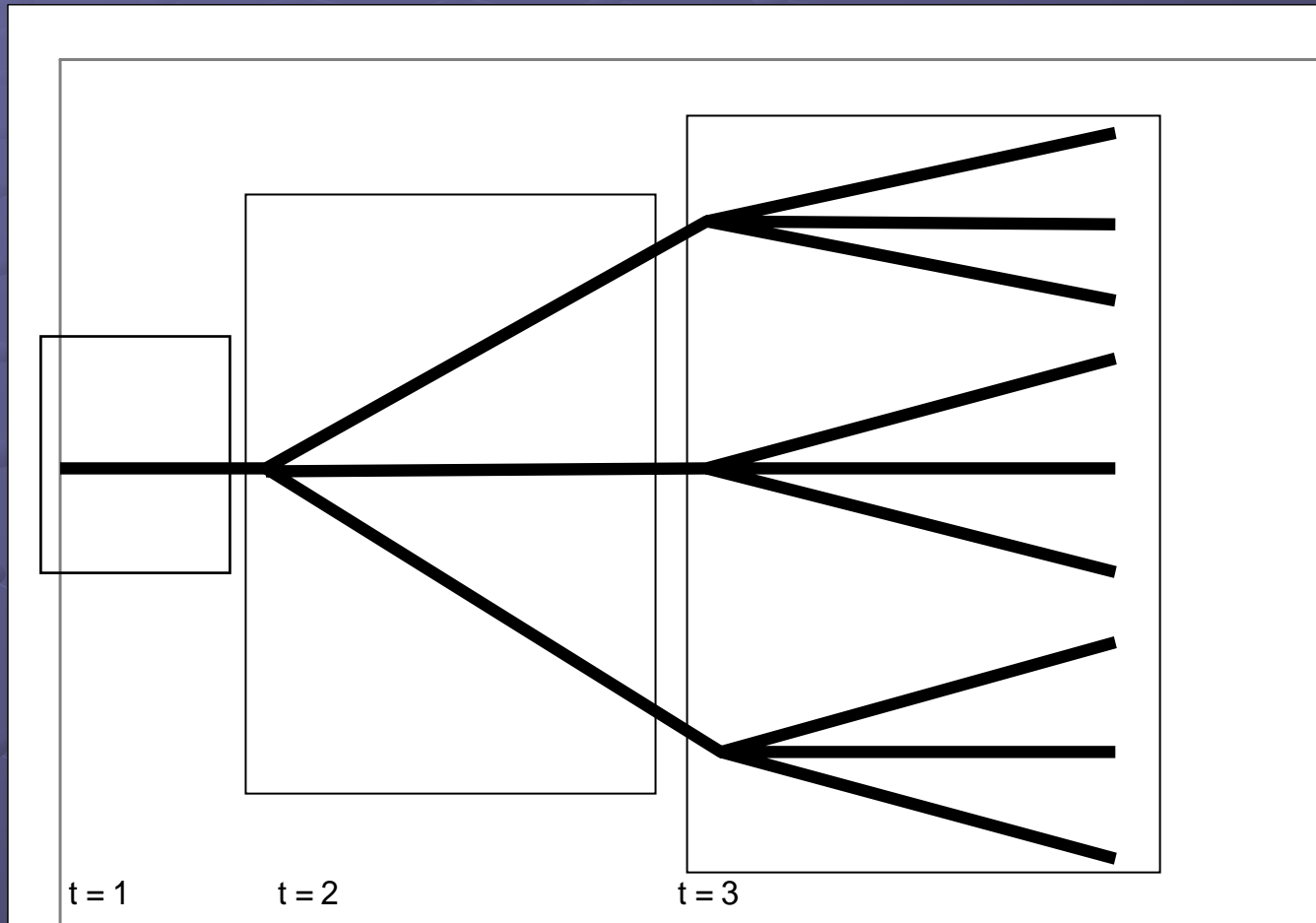
SDP (cont.)

- Suppose $X = 20$ intervals of discretization
 - 1 reservoir $\Rightarrow 20^2 = 400$ states
 - 2 reservoirs $\Rightarrow 20^4 = 160$ thousand states
 - 3 reservoirs $\Rightarrow 20^6 = 64$ million states
 - 4 reservoirs $\Rightarrow 20^8 = 25$ billion states
 - 5 reservoirs $\Rightarrow 20^{10} = 10$ trillion states
- Computationally infeasible for even small reservoir systems

Alternative: Stochastic Programming with Recourse (SPR)

- Modeling under uncertainty
- Maximizing over a number of scenarios
- Maximizing current period plus expected value of future periods.
- Avoids the curse of dimensionality by constructing an approximation of the future value function from shadow price information gathered from the linear program (**CUTS**)
a.k.a. *Bender's Decomposition*

SPR tree within framework of this research



SPR: Benders Decomposition Approach

- Algorithm decomposes into a collection of subproblems by stage and scenario
- Each subproblem requires initial reservoir storages
- After solving subproblem:
 - pass ending storage values to the next scenario
 - pass “cuts” to previous scenario
- Solved iteratively by “tree traversing strategies” until a first stage solution is converged upon

Subproblem Objective Function

sub (ω_t)

$$\text{Max } c_t x_t + \sum_{\omega \in \text{scenarios}} P_{\omega,t+1} f_{\omega,t+1}$$

$$A_t x_t = b_t(\omega_t) + B_t x_{t-1}$$

$$x_t \geq 0$$

$$f_{\omega,t+1} \leq \text{Obj}'_{\omega,t+1} + \sum_r \pi'_{r,\omega} (S_r - S'_r) \forall \omega_{t+1} | \omega_t$$

where

c_t = a vector of first period objective function coefficients

x_t = a vector of first period decision variables

ω_t = scenario index

P_{ω} = Probability of particular scenario

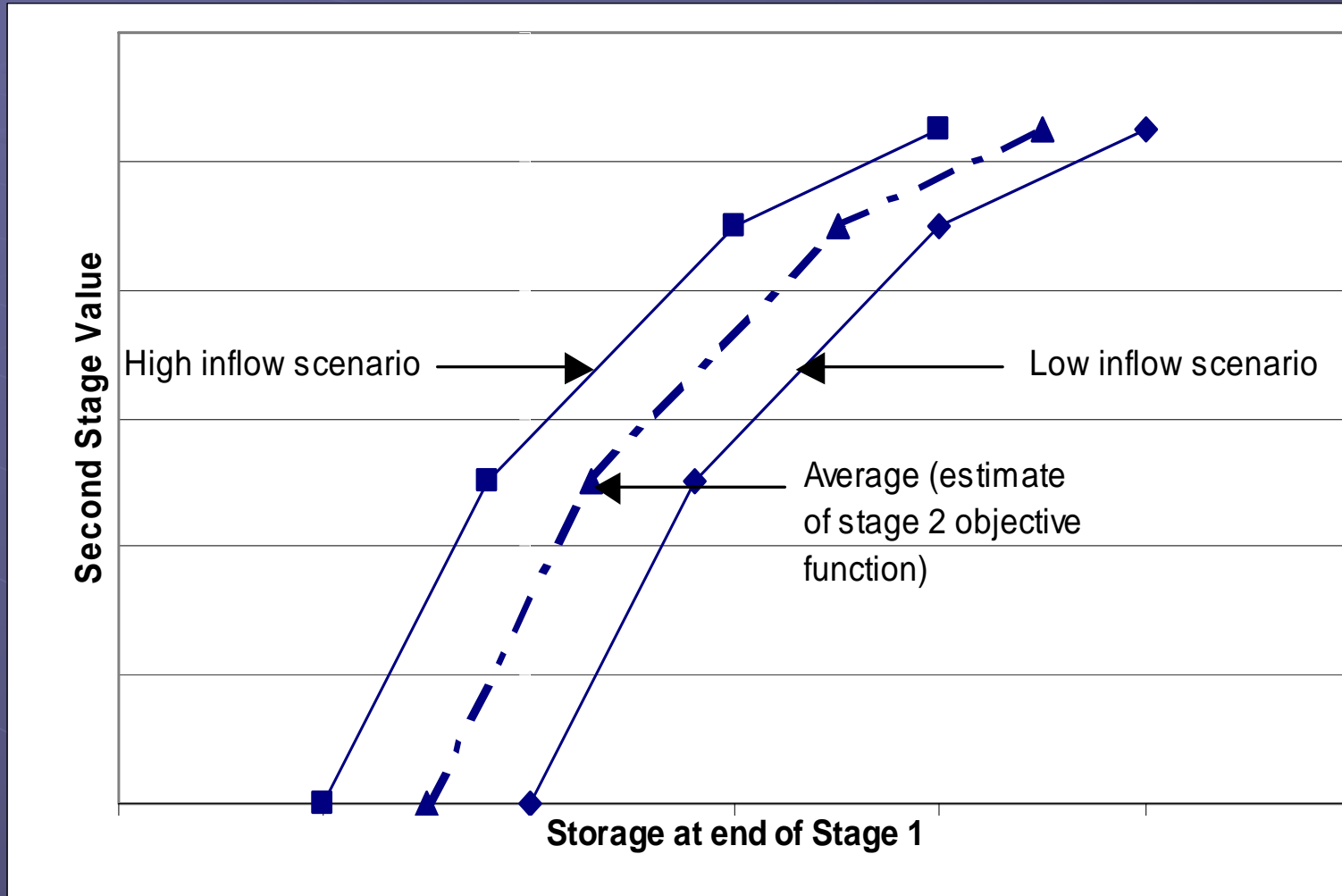
f_{ω} = future value under scenario ω

π = dual price from stage $t+1$ solution

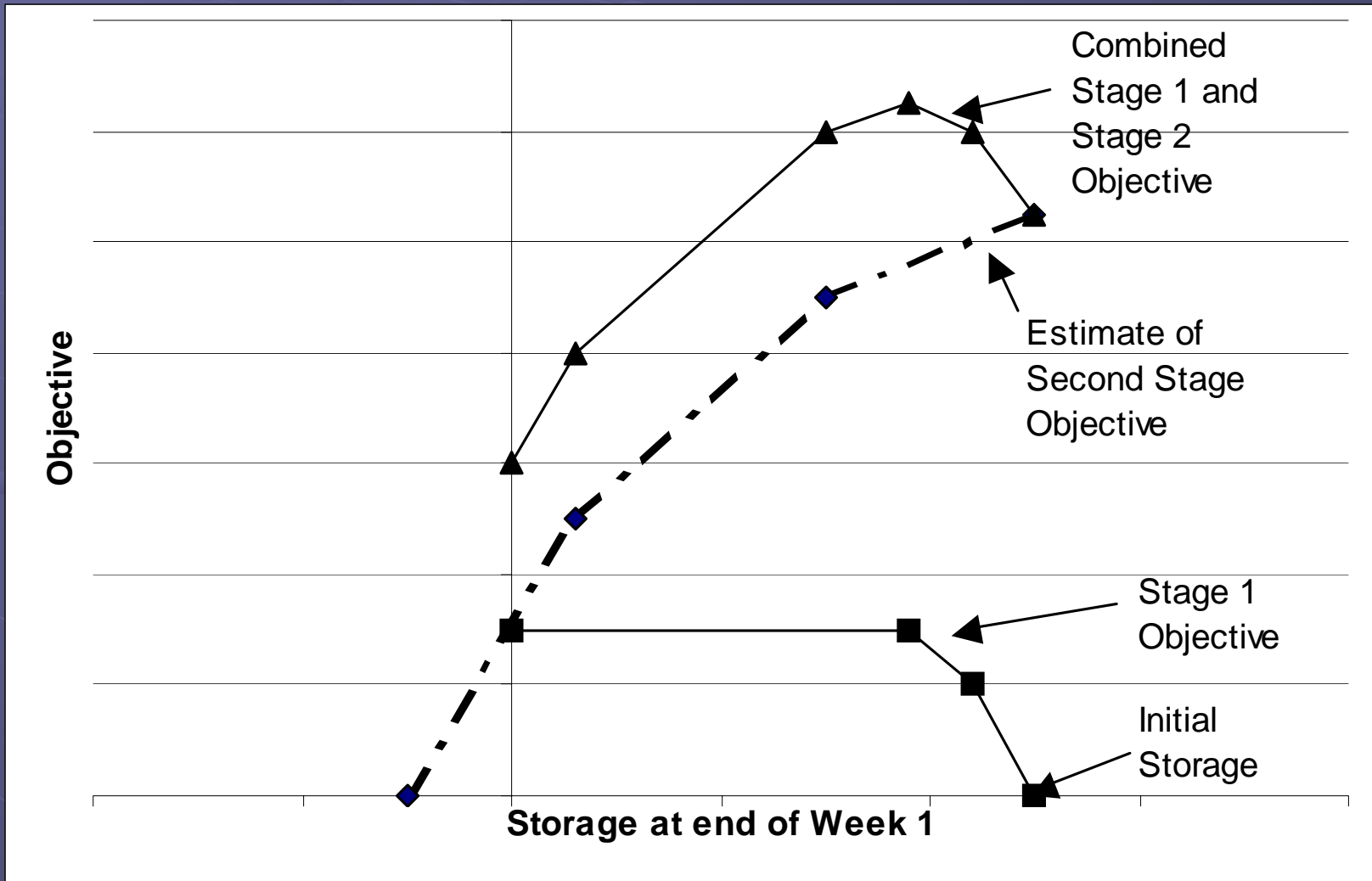
S_r = Storage at end of current stage (variable)

S'_r = Storage at beginning of next stage that produced this cut

Estimate of stage 2 objective function



Maximize combined stage 1 and stage 2 objective function



SPR Challenge

- Size of scenario tree grows exponentially as number of stages increases
- i.e. Problem with three scenarios per stage

2nd Stage:3 scenarios

3rd Stage:9 scenarios

4th Stage:27 scenarios

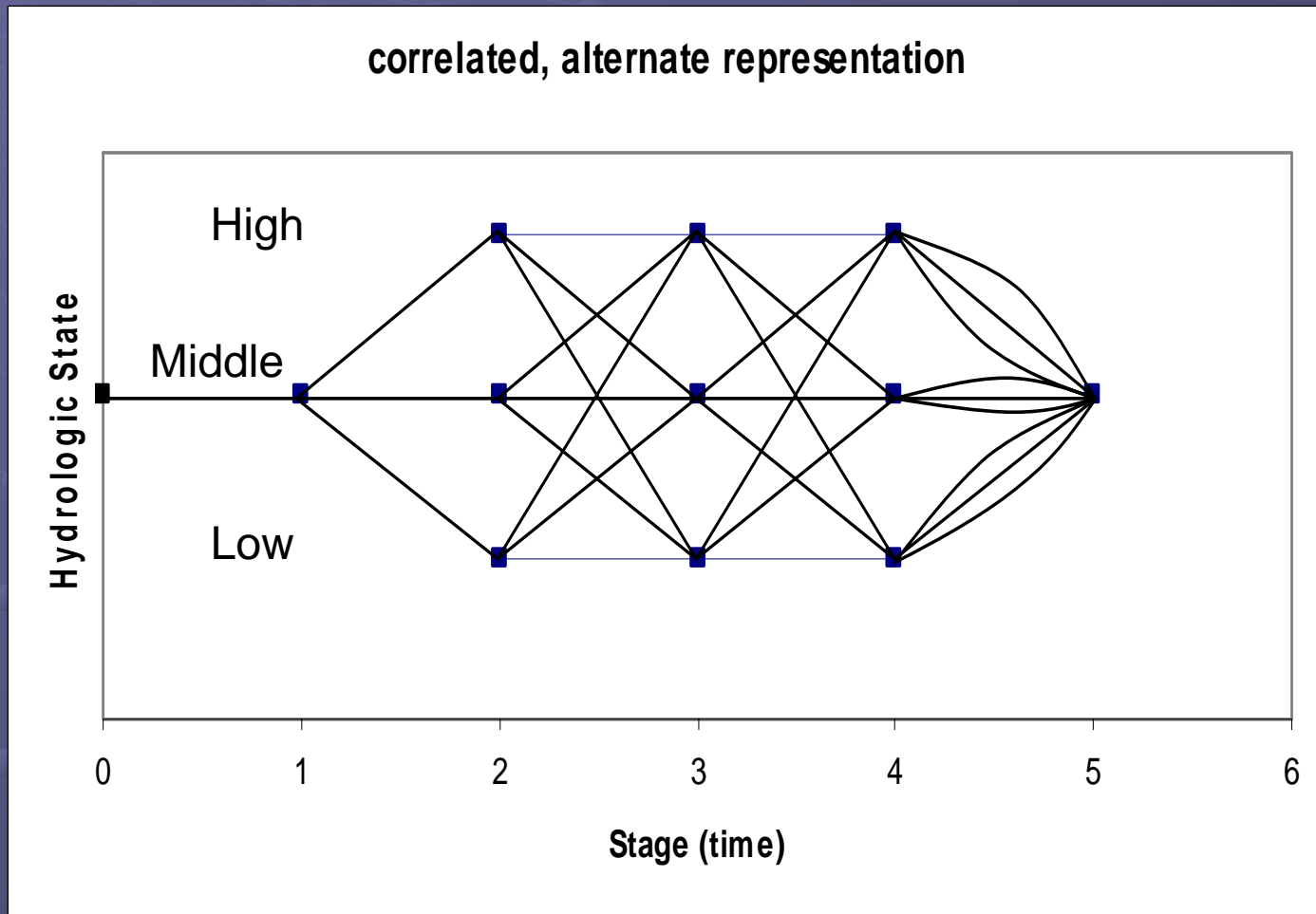
5th Stage:81 scenarios

Network Stochastic Programming – Main Idea

Alternative Representation of SPR tree

- Use hydrologic state to reduce trees to network of states
 - Future value at a state is a function of storage but otherwise independent of path: increased cut sharing
- Intentionally simple definition of state (not focus of this research)
 - Function of historical flows for each week
 - Historical flow mapped into exactly one state for each week
 - Transitional arc between each state
- TVA uses a state definition concept for forecasting

Correlated multistage alternate representation for stochastic model



Iteration

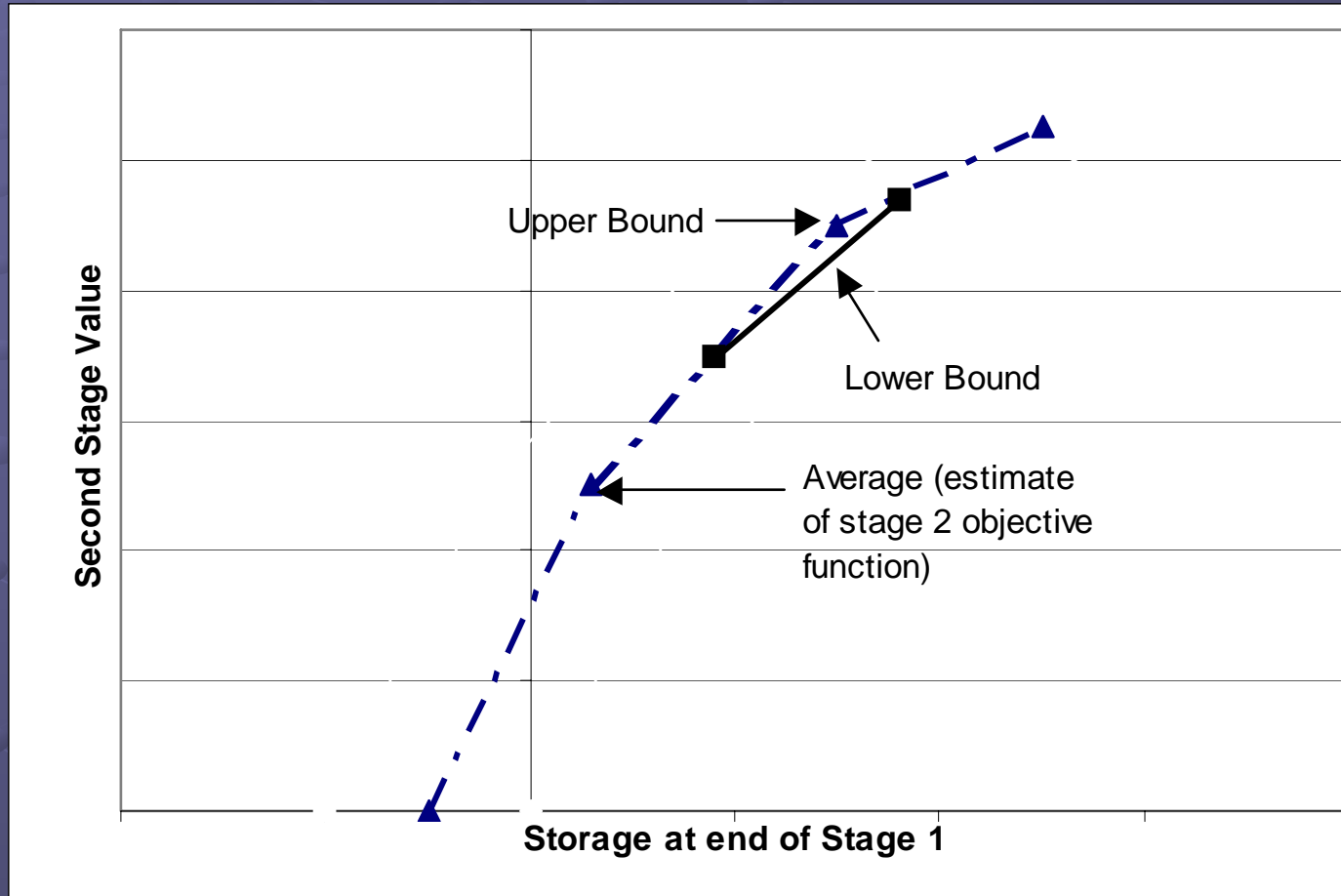
- Determined initial storages on first forward pass
- Solve last stage and pass cuts to the preceding stage
- Continue procedure backward and forward, adding cuts after each problem solved
- End when solution converges

Convergence

- Convergence requires an upper bound (UB), lower bound (LB), and Gap Tolerance.
- Program terminates when bounds are within the gap tolerance:

$$UB - LB \leq \text{Gap Tolerance}$$

Visual Representation of lower bound



Status

- **In testing now with TVA data**

- **Accomplished:**

- 4-week Model
 - Generate Cuts for single reservoir
 - Single Objective

- **To Do:**

- Longer Model (6 – 8 weeks)
 - Cuts for all storage reservoirs (UB)
 - Compute a lower bound
 - Multiple Objective

- **Future Implementation**

- Proof of Concept
 - No GUI representation
 - Not Efficient

Summary

- NSP provides a Stochastic Optimization Solution
- Avoids the problems historically associated with SDP and SPR
- With appropriate enhancement could be a very valuable RiverWare tool